

$$2. X_{com} = ? \quad X_{com} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{m_1 + m_2 + m_3}$$

$$X_{com} = \frac{(3)(0) + (4)(2) + (8)(1)}{15} = \frac{16}{15} = 1.07 \text{ m}$$

$$b) Y_{com} = ? \quad Y_{com} = \frac{(3)(0) + (4)(1) + (8)(2)}{15} = \frac{20}{15} = 1.33 \text{ m}$$

c) if m_3 gains mass (how does that then the com moves happen?)
toward m_3

4. $r_{com} = ?$ (in comp. form)

$$X_{com} = \frac{m_1 X_1 + m_2 X_2 + m_3 X_3}{M}$$

$$= \frac{(0.014)(0) + (0.042)(0.11) + (0.014)(0.22)}{0.076}$$

$$X_{com} = 0.11 \text{ m (which I could have "guessed" at using symmetry!)}$$

$$Y_{com} = \frac{(0.014)(-0.11) + (0.042)(0) + (0.014)(-0.11)}{0.076}$$

$$= -0.044 \text{ m}$$

$$\underline{r_{com} = 11 \text{ cm} \hat{i} - 4.4 \text{ cm} \hat{j}}$$

7. $\vec{r}_{com} = ?$

$x_{com} = 0$ (symmetry)

$$y_{com} = \frac{m_1 y_1 + m_2 y_2}{M} = \frac{(3m)(0) + (13.9m)(3.80 \times 10^{-11})}{16.9m}$$

$y_{com} = 3.13 \times 10^{-11} \text{ m}$

$$6. \quad a) \quad X_{\text{com}} = ? \quad X_{\text{com}} = \frac{\sum_{i=1}^5 m_i x_i}{M}$$

$$X_{\text{com}} = \frac{m(L) + m(L/2) + m(0) + m(L/2) + m(L/2)}{5m}$$

$$X_{\text{com}} = \frac{\frac{5L}{2}}{5} = \frac{L}{2} = \frac{40\text{cm}}{2} = 20\text{cm} = X_{\text{com}}$$

$$Y_{\text{com}} = ? = 20\text{cm} \text{ (by symmetry!)} \quad \uparrow$$

c) $Z_{com} = ?$

$$Z_{com} = \frac{m(0) + 4[m(1/2)]}{5m} = \frac{2mL}{5m} = \frac{2}{5}L$$

$$= \frac{2}{5}(40_{cm}) = 16cm = Z_{com}$$